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(54) ROBOT CLEANER AND CONTROLLING METHOD THEREOF

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(57) ABSTRACT

Embodiments of the present disclosure relate to a robot cleaner and a control method of the robot cleaner, more particularly, to a robot cleaner configured to correct position information of the robot cleaner by acquiring a position of a docking station during the robot clear drives and to correct a map by using corrected position information, and a control method of the robot cleaner.

